

Team	Number	Attempt 1					Attempt 2					Results		
		Time	DOO	OC	USS	Status	Time	DOO	OC	USS	Status	Best	Score	Place
KA-Racelng	E76	00:22.95	1	0	0		---	---	---	---	---	24,95	175,0	1
Revolve NTNU	E63	00:30.63	1	0	0		00:26.95	0	0	0		29,79	141,6	2
Chalmers Formula Student	E95	00:47.80	0	0	0	DNF	00:25.49	0	0	0	---	36,65	94,4	3
Mainfranken Racing e.V.	E97	00:31.46	4	0	0	---	00:31.40	2	0	0	---	37,43	89,0	4
Ecurie Aix Formula Student Team RWTH Aachen	E9	00:47.80	0	0	0	DNF	00:30.08	3	1	0	---	46,94	23,4	5
Fast Forest	E44	00:28.99	0	0	0	DNF	00:29.32	0	0	0	DNF	---	0,0	6
PWR Racing Team	E15	---	---	---	---	---	---	---	---	---	---	---	0,0	6
UMD Racing e.V.	E20	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Formula Electric Belgium	E22	---	---	---	---	---	---	---	---	---	---	---	0,0	6
FS Team Tallinn	E24	---	---	---	---	---	---	---	---	---	---	---	0,0	6
AMZ Racing	E33	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Schanzer Racing Electric e.V.	E34	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Lund Formula Student	E39	---	---	---	---	---	---	---	---	---	---	---	0,0	6
TU Darmstadt Racing Team	E40	---	---	---	---	---	---	---	---	---	---	---	0,0	6
eForce Prague Formula	E42	---	---	---	---	---	---	---	---	---	---	---	0,0	6
NTHU Racing	E4	---	---	---	---	---	---	---	---	---	---	---	0,0	6
UGent Racing	E51	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Elbflorace e.V. Formula Student Team Dresden	E59	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Dynamics e.V.	E62	---	---	---	---	---	---	---	---	---	---	---	0,0	6
CURE Mannheim e.V.	E71	---	---	---	---	---	---	---	---	---	---	---	0,0	6
e-gnition Hamburg e. V.	E78	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Formula Student Team Delft	E85	---	---	---	---	---	---	---	---	---	---	---	0,0	6
Dynamis PRC	E90	---	---	---	---	---	---	---	---	---	---	---	0,0	6
High-Voltage Motorsports e.V.	E94	---	---	---	---	---	---	---	---	---	---	---	0,0	6

Time T_{max}=47.8s was replaced for runs which qualifies according to rule D6.3.2 (runs with DNF or time greater than T_{max})